

Radius of curvature

Basic gear formulas:

$$D_p = \frac{Z}{d_0}$$

$$d_b = d_0 * \cos \phi \text{ [in.]}$$

$$t = \frac{\pi}{2D_p} \text{ [in.]}$$

Conversion from degrees to radians:

$$\hat{\phi} = \frac{\pi\phi}{180} \text{ [rad.]}$$

Where:

Z – number of teeth

d_0 – pitch diameter [in.]

d_b – base diameter [in.]

D_p – diametral pitch [dimensionless]

ϕ – pressure angle [degree]

t – CTT, circular tooth thickness [in.]

General form of an involute function:

$$\hat{\theta} = \text{inv}\phi = \tan \phi - \hat{\phi}$$

Where:

$\hat{\theta}$ – polar angle [radians]

θ – polar angle [degree]

$\text{inv}\phi$ – involute function of an angle [rad.]

ϕ – involute pressure angle [degree]

$\hat{\phi}$ – involute pressure angle [radians]

Radius of curvature at an arbitrary point on the involute curve:

$$\rho_A = (R_A^2 - R_b^2)^{0.5}$$

Where:

ρ_A – radius of curvature, at point "A" on the involute

R_A – radius to point "A"

R_b – base radius

This could be expressed as a function of the pressure angle:

$$\rho_A = R_A * \sin \phi_A$$

Where:

ϕ_A – pressure angle at point "A"

Radius of curvature at pitch diameter:

$$\rho = \frac{d * \sin \phi}{2}$$

Where: ρ – radius of curvature

d – pitch diameter

ϕ – pressure angle at pitch diameter

NOTE:

As $R_b \rightarrow \infty$ the $\rho \rightarrow \infty$ and therefore the tooth shape becomes a straight line as in the basic involute rack

Involute

radius of curvature " ρ " at point "A"

$\theta = \text{inv}\Phi_A$

R_A

Base radius R_b

Φ_A

A

